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## PDE FOR APPS F 08, HW12 SOLUTION

Below is a link to a Java applet I found that graphs phase portraits.

<http://www.math.psu.edu/melvin/phase/newphase.html>

9.1:1 To find eigenvalues observe that

$$\det(A - \lambda I) = \det \begin{pmatrix} 3 - \lambda & -2 \\ 2 & -2 - \lambda \end{pmatrix} = (\lambda - 3)(2 + \lambda) + 4 = \lambda^2 - \lambda - 2 = (\lambda - 2)(\lambda + 1).$$

Therefore  $r_1 = 2 > 0 > r_2 = -1$  and  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is a saddle point and is unstable. As for eigenvalues we need to solve  $Av = \lambda v$ . It's clear that the vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  is not an eigenvector, therefore we may assume that  $v = \begin{pmatrix} 1 \\ v_2 \end{pmatrix}$ . Letting  $\lambda = r_1 = 2$  we see that  $3 - 2v_2 = 2$  hence  $v_2 = \frac{1}{2}$ . Letting  $\lambda = r_2 = -1$  we see that  $3 - 2v_2 = -1$  therefore  $v_2 = 2$ . Summarizing:  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  is eigenvector for  $r_1 = 2$  and  $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$  is eigenvector for  $r_2 = -1$ .

9.1:4

$$\det(A - \lambda I) = \det \begin{pmatrix} 1 - \lambda & -4 \\ 4 & -7 - \lambda \end{pmatrix} = (\lambda - 1)(7 + \lambda) + 16 = \lambda^2 + 6\lambda + 9 = (\lambda + 3)(\lambda + 3).$$

Therefore  $r_1 = r_2 = -3$ . As for eigenvalues we need to solve  $Av = -3v$ . It's clear that the vectors  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ ,  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  are not eigenvectors, therefore we may assume that  $v = \begin{pmatrix} 1 \\ v_2 \end{pmatrix}$ ,  $v_2 \neq 0$ . We see that  $4 - 7v_2 = -3v_2$  hence  $v_2 = 1$ . This shows that there's only one independent vector. We may then choose the eigenvector to be  $v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ . At this stage we are able to conclude that  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is an improper sink and is asymptotically stable. We seek for the generalized eigenvector, obtained by  $(A + 3I)u = v$ . Since all solutions to this equation differ by a constant multiple of  $v$  (why? the null space of  $(A + 3I)$  is spanned by  $v$ ) there exists a solution of the form  $u = \begin{pmatrix} 0 \\ u_2 \end{pmatrix}$  (one can always add a constant multiple of  $v$  to make the first component equal to 0). The equation for  $u_2$  is  $4 * 0 - 4u_2 = 1$ . Therefore  $u = \begin{pmatrix} 0 \\ -\frac{1}{4} \end{pmatrix}$ .

9.1:12

$$\det(A - \lambda I) = \det \begin{pmatrix} 2 - \lambda & -\frac{5}{2} \\ \frac{9}{5} & -1 - \lambda \end{pmatrix} = \lambda^2 - \lambda + \frac{5}{2} = \left(\lambda - \frac{1}{2}\right)^2 + \frac{9}{4}.$$

Hence  $\lambda - \frac{1}{2} = \pm \frac{3i}{2}$ . In particular  $r_{1,2} = \frac{1}{2}(1 \pm 3i)$ , and we conclude that  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is a spiral source. Therefore it is unstable.

9.1:15 First we find the critical point by solving

$$\begin{pmatrix} -1 & -1 \\ 2 & -1 \end{pmatrix} v + \begin{pmatrix} -1 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix},$$

where  $v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$ . Thus  $-v_1 - v_2 = 1$  and  $2v_1 - v_2 = -5$ . Subtracting the second equation from the first we obtain  $-3v_1 = 6$ , so  $v_1 = -2$ , which implies  $v_2 = 1$ . Therefore  $v = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$  is the only critical point. We now linearize the system. Define  $\tilde{\mathbf{x}} = \mathbf{x} - v$ . Then

$$\begin{aligned} \frac{d\tilde{\mathbf{x}}}{dt} &= \begin{pmatrix} -1 & -1 \\ 2 & -1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} -1 \\ 5 \end{pmatrix} = \begin{pmatrix} -1 & -1 \\ 2 & -1 \end{pmatrix} (\tilde{\mathbf{x}} + v) + \begin{pmatrix} -1 \\ 5 \end{pmatrix} \\ &= \begin{pmatrix} -1 & -1 \\ 2 & -1 \end{pmatrix} \tilde{\mathbf{x}} + \underbrace{\begin{pmatrix} -1 & -1 \\ 2 & -1 \end{pmatrix} v + \begin{pmatrix} -1 \\ 5 \end{pmatrix}}_{=0}. \end{aligned}$$

Finally,

$$\det \begin{pmatrix} -1 - \lambda & -1 \\ 2 & -1 - \lambda \end{pmatrix} = (1 + \lambda)^2 + 2.$$

Therefore  $\lambda = -1 \pm i\sqrt{2}$ , from which we conclude that  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$  is a spiral sink for  $\tilde{\mathbf{x}}$ , which is equivalent to the statement that  $v$  is a spiral sink for  $\mathbf{x}$ . This critical point is asymptotically stable.